

## ANTONIO – Multimodal sensing for individual pIANT phenotyping iN agriculture robOtics



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### Involved countries and partners











Aristotle University of Thessaloniki

Laboratory for Alternative Energy Sources in Agriculture (AUTH-AESA) [Greece]

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Politecnico di Bari

Department of Mechanics, Mathematics, and Management (POLIBA) [Italy]

> Principal Researcher Giulio Reina, Professor

National Research Council of Italy

Institute of Intelligent Industrial Technologies and Systems for Advanced Manufacturing (STIIMA) [Italy]

> Principal Researcher Dr. Annalisa Milella

Fraunhofer Institute for Intelligent Analysis and Information Systems IAIS (FRA) [Germany]

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Principal Researcher Dr. rer. nat. Stefan Rilling AgriCircle

Leading provider of technologies for a more productive and sustainable agriculture (AC) [Switzerland]

> Principal Researcher Dr. Peter Fröhlich

Duration: 24 months (March 2021 to February 2023)

### Overall budget: 693.5K €



### Objective

The overall goal of ANTONIO project was the development and implementation of multi-sensor systems and sensor processing algorithms to enable agri-robots to perform plant phenotyping and precision agriculture tasks, such as precise local application of pesticides/fertilizers and yield estimation.





The envisaged idea was based on an integrated sensor network, including mobile sensors mounted on board of ground robots and drones. Information coming from the fixed sensing devices was flagging "attention spots" in the crop for further local investigation by the robotic platforms.



### Selected research approach, methodology





Sensor	Description	Sensor	Description
Differential GPS	Rover system w/base station, providing single precision accuracy of approximately 2.5 m and RTK accuracy of approximately 0.25m	Commercial Drone Model	Parrot Bluegrass Field
9-DoF IMU	Inertial sensor w/gyroscope, accelerometer, and magnetometer		Sequoia Multispectral Camera, 4 Separate Bands [Green: 550nm +/- 40nm, Red: 660 nm +/- 40nm, Red Edge: 735nm +/- 10nm, Near Infrared: 790nm +/- 40nm]
2D LIDAR Sick LMS 111	Set for outdoor environments	Onboard Cameras	
Rotary Encoders	Mounted on the sprocket of each track		
Traction Motor Sensors	Measuring electric current absorbed by the traction motors	UGV multisensory system tested in lab and field for effectiveness	
Intel RealSense D400	Camera providing multiple outputs including RGB, IR, and depth images	Sensors synchronized and spatially calibrated for data consistency	
		• Development of self-calibration method for merging "point-clouds" from stereo sensors	
Onboard computer	Intel i7 CPU, 16GB RAM DDR, 256GB SSD, Wi-Fi and BT connectivity	Algorithm development and validation through numerical simulations and lab tests	
Power Supply	24V DC 30A LiPo battery package (3 hrs autonomy)		

# Major results: Highlight key accomplishments and challenges faced

### Field Tests and Data Acquisition

- Initial Field tests conducted in private and experimental vineyards
- Successfully verified of the proper functioning of all system components

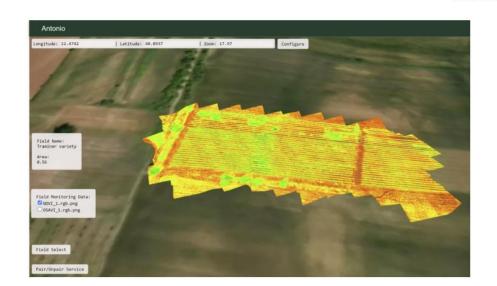
### **Spectral Image Processing and Feature Extraction**

- Spectral conversion of RGB images to spectral bands
- Successful extraction of features from spectral images characterizing crop health and condition (NDVI, GNDVI, SAVI, CI, OSAVI, TCARI)

### Decision Support System (DSS, ANTONIO Platform)

- Utilization of PIX4Dfield software for map processing and integration into the ANTONIO platform
- Access to live data for different fields







# Cooperation with stakeholders, industry partners and/or public and private sector (if applicable)

### 1<sup>st</sup> Cluster Workshop

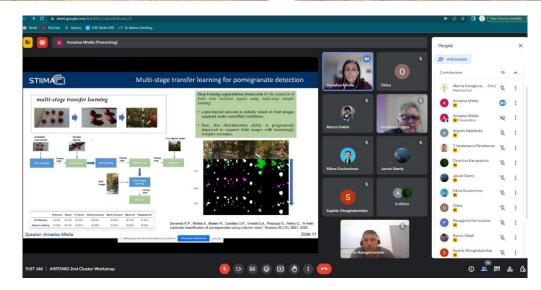
The primary objective of this workshop was to engage farmers, stakeholders, and key actors in the agricultural sector to provide them with a comprehensive understanding of the ANTONIO project, its objectives, and its wide range applications in precision agriculture.



### 2<sup>nd</sup> Cluster Workshop

The purpose of the workshop was to present an overview of the project's activities and summarize all work done by partners in one conclusive meeting. In this conclusive workshop all partners of the project had the chance to present their work to the rest of the participants and share their thoughts on the outcome, provide insights about future work, and discuss means of implementation of the project's outcomes.







### Opportunities and next steps for innovation

#### Scalability and Cost Optimization

- •Develop strategies for scalability and cost-effectiveness.
- •Conduct a cost-benefit analysis, explore cost-saving technologies, and design scalable architectures.

### Efficient Data Management

- •Enhance data management capabilities.
- Develop advanced data management solutions, explore cloud-based storage, and implement encryption protocols.

### Integration with Existing Farming Practices

- Ensure smooth integration with existing farming practices.
- Conduct user experience studies, gather farmer feedback, and provide training for seamless adoption.

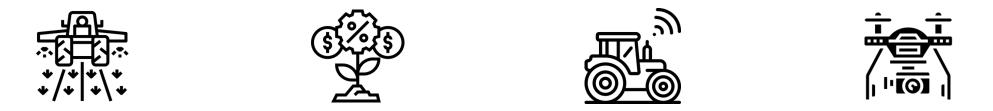
### Compliance with Regulations and Safety Standards

- •Ensure compliance with regulations and safety standards.
- •Stay informed about regulations, collaborate with regulatory bodies, and implement and audit safety features.

## Summary and Conclusion takeaways and lessons learned



The ANTONIO project represents a transformative leap in precision agriculture, offering unprecedented capabilities in crop monitoring and disease detection.



To ensure its effectiveness and sustainability, addressing key challenges such as scalability, data management, integration, and regulatory compliance is imperative. By focusing on these areas, the project can not only unlock its full potential but also contribute significantly to advancing modern agriculture and fostering a more sustainable and resilient food system.



## LET'S KEEP IN TOUCH!

Please feel always free to reach out to us.

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### Thank you for your attention!